# Theory and numerics of solitary waves: Talk about split-step methods

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## 1 Notation

We consider an autonomous problem

$$\dot{y} = f(y), \quad y(t_0) = y_0$$
 (1)

where  $f : \mathbb{R}^n \to \mathbb{R}^n$  is sufficiently differentiable.

We denote its exact flow by  $\varphi_t$ .  $\Phi_h$  will refer to a numerical one-step method with step-size h.

The *adjoint method*  $\Phi_h^*$  of a method  $\Phi_h$  is the inverse map of the original method with reversed time step -h, i.e.,

$$\Phi_h^* := \Phi_{-h}^{-1}.$$

In other words,  $y_1 = \Phi_h^*(y_0)$  is implicitly defined by  $\Phi_{-h}(y_1) = y_0$ . A method for which  $\Phi_{*h} = \Phi_h$  is called *symmetric*.

Note that  $\varphi_{-t}^{-1} = \varphi_t$ , but in general  $\Phi_h^* = \Phi_{-h}^{-1} \neq \Phi_h$ . The adjoint method satisfies  $(\Phi_h^*)^* = \Phi_h$  and  $(\Phi_h \circ \Psi_h)^* = \Psi_h^* \circ \Phi_h^*$ .

**Theorem 1** Let  $\varphi_t$  be the exact flow (1) and let  $\Phi_h$  be a one-step method of order p satisfying

$$\Phi_h(y_0) = \varphi_h(y_0) + C(y_0)h^{p+1} + \mathcal{O}(h^{p+1}).$$

The adjoint method  $\Phi_h^*$  then has the same order p and we have

$$\Phi_h^*(y_0) = \varphi_h(y_0) + (-1)^p C(y_0) h^{p+1} + \mathcal{O}(h^{p+1}).$$

If the method is symmetric, its (maximal) order is even.

The proof can be found in [1], Section II.3.

## 2 Split-Step Methods

Once decomposes the vector field into integrable pieces and treats them separately.

We consider an arbitrary system  $\dot{y} = f(y)$  in  $\mathbb{R}^n$ , and suppose that the vector field is "split" as

$$\dot{y} = f^{[1]}(y) + f^{[2]}(y).$$
 (2)

It then, by chance, the exact flows  $\phi_t^{[1]}$  and  $\Phi_t^{[2]}$  of the systems  $\dot{y} = f^{[1]}(y)$  and  $\dot{y} = f^{[2]}(y)$  can be calculated explicitly, we can, from a given initial value  $y_0$ , first solve the first system to obtain a value  $y_{1/2}$ , and from this value integrate the second system to obtain  $y_1$ . In this way we have introduced the numerical methods

$$\Phi_{h}^{*} = \varphi_{h}^{[2]} \circ \varphi_{h}^{[1]} 
\Phi_{h} = \varphi_{h}^{[1]} \circ \varphi_{h}^{[2]}$$
(3)

where one is the adjoint of the other. These formulas are often called the *Lie-Trotter splitting* (Trotter 1959). By Taylor expansion we find that  $(\varphi_h^{[1]} \circ \varphi_h^{[2]})(y_0) = \varphi_h(y_0) + \mathcal{O}(h^2)$ , so that both methods give approximations of order 1 to the solution of (2). Another idea is to use a symmetric version and put

$$\Phi_h^{[S]} = \varphi_{h/2}^{[1]} \circ \varphi_h^{[2]} \circ \varphi_{h/2}^{[1]}, \tag{4}$$

which is known as the *Strang splitting* (Strang 1968), and sometimes as the *Marchuk splitting* (Marchuk 1968). By breaking up in (4)  $\varphi_h^{[2]} = \varphi_{h/2}^{[2]} \circ \varphi_{h/2}^{[2]}$ , we see that the Strang splitting  $\Phi_h^{[S]} = \Phi_{h/2} \circ \Phi_{h/2}^*$  is the composition of the Lie-Trotter method and its adjoint with halved step sizes. The Strang splitting formula is therefore symmetric and of order 2.

## 2.1 General Splitting Procedure

In a similar way to the general idea of composition methods, we can form with arbitrary coefficients  $a_1, b_1, a_2, \ldots, a_m, b_m$  (where, eventually,  $a_1$  or  $b_m$ , or both, are zero)

$$\Psi_{h} = \varphi_{b_{m}h}^{[2]} \circ \varphi_{a_{m}h}^{[1]} \circ \varphi_{b_{m-1}h}^{[2]} \circ \cdots \circ \varphi_{a_{2}h}^{[1]} \circ \varphi_{b_{1}h}^{[2]} \circ \varphi_{a_{1}h}^{[1]}$$
(5)

and try to increase the order of the scheme by suitably determining the free coefficients. We will show a method how to do that later.

There is a close connection between the theories of splitting methods and of composition methods. If we put  $\beta_1 = a_1$  and break up  $\varphi_{b_1h}^{[2]} = \varphi_{\alpha_1h}^{[2]} \circ \varphi_{\beta_1h}^{[2]}$  (group property of the exact flow) and so on, we see that with

$$\Phi_h = \varphi_h^{[1]} \circ \varphi_h^{[2]} \quad \text{so that} \quad \Phi_h^* = \varphi_h^{[2]} \circ \varphi_h^{[1]} \tag{6}$$

 $\Psi_h$  is identical with the  $\Psi_h$  of a composition method. The  $\alpha$ s and  $\beta$ s for m=3 are given below.

$$a_{1} = \beta_{1}$$

$$b_{1} = \beta_{1} + \alpha_{1}$$

$$a_{2} = \alpha_{1} + \beta_{2}$$

$$b_{2} = \beta_{2} + \alpha_{2}$$

$$a_{3} = \alpha_{2} + \beta_{3}$$

$$b_{3} = \beta_{3}$$

$$(7)$$

A necessary and sufficient condition for the existence of  $\alpha_i$  and  $\beta_i$  satisfying (7) is that  $\sum a_i = \sum b_i$ , which is the consistency condition anyway for (5).

### 2.2 Combining Exact and Numerical Flows

It may happen that the differential equation  $\dot{y} = f(y)$  can be split according to (2), such that only the flow of, say,  $\dot{y} = f^{[1]}(y)$  can be computed exactly. If  $f^{[1]}(y)$  constitutes the dominant part of the vector field, it is natural to search for integrators that exploit this information. We just consider

$$\Phi_h = \varphi_h^{[1]} \circ \Phi_h^{[2]}, \quad \Phi_h^* = \Phi_h^{[2]*} \circ \varphi_h^{[1]}$$
(8)

as the basis of the composition method. Here  $\varphi_t^{[1]}$  is the exact flow of  $\dot{y} = f^{[1]}(y)$ , and  $\Phi_h^{[2]}$  is some first-order integrator applied to  $\dot{y} = f^{[2]}(y)$ . Since  $\Phi_h$  of (8) is consistent with (2), the resulting method has the desired high order. It is given by

$$\Psi_{h} = \varphi_{\alpha_{s}h}^{[1]} \circ \Phi_{\alpha_{s}h}^{[2]} \circ \Phi_{\beta_{s}h}^{[2]*} \circ \varphi_{(\beta_{s}+\alpha_{s-1})2h}^{[1]} \circ \Phi_{\alpha_{s-1}1h}^{[2]} \circ \cdots \circ \Phi_{\beta_{1}h}^{[2]*} \circ \varphi_{\frac{\beta_{1}h}{1}}^{[1]}.$$
(9)

Notice that replacing  $\varphi_t^{[2]}$  with a low-order approximation  $\Phi_t^{[2]}$  in (5) would not retain the high order of the composition, because  $\Phi_t^{[2]}$  does not satisfy the group property.

## 2.3 Splitting into More than Two Vector Fields

Consider a differential equation

$$\dot{y} = f^{[1]}(y) + f^{[2]}(y) + \dots + f^{[N]}(y),$$
(10)

where we assume that the flows  $\varphi_t^{[j]}$  of the individual problems  $\dot{y} = f^{[j]}(y)$  can be computed exactly. In this case there are many possibilities for extending (5) and for writing the method as a composition of  $\varphi_{a_jh}^{[1]}, \varphi_{b_jh}^{[2]}, \varphi_{c_jh}^{[3]}, \ldots$  This makes it difficult to find optimal compositions of high order. A simple and efficient way is to consider the first-order method

$$\Phi_h = \varphi_h^{[1]} \circ \varphi_h^{[2]} \circ \dots \circ \varphi_h^{[N]}$$
(11)

together with its adjoint as the basis for a composition method. Without any additional effort this yields splitting methods for (10) of arbitrary high order.

# 3 Example: Low order splitting methods for the 1D Nonlinear Schrödinger Equation (NLS)

For repetition: the 1D nonlinear Schrödinger equation

$$iu_t + u_{xx} + |u|^2 u = 0 (12)$$

It will be convenient to rewrite the NLS to

$$u_t = i\mathcal{L}u + i\mathcal{N}(u)u, \qquad -\infty < x < \infty, \tag{13}$$

where

$$\mathcal{L}u := u_{xx} \qquad \mathcal{N}(u) := |u|^2 \tag{14}$$

As a first step, we see, that the solution of (12) may be advanced from one time-level to the next by means of the following formula

$$u(x,t+\tau) \approx e^{i\tau(\mathcal{L}+\mathcal{N}(u))} \cdot u(x,t), \tag{15}$$

where  $\tau$  denotes the timestep. In general (15) is first order accurate, but under scpecial circumstances  $|u|^2$  is time-independent in which case (15) turns out to be exact.

The time-splitting procedure now consists of replacing the right-hand side of (15) by

$$e^{i\tau(\mathcal{L}+\mathcal{N}(u))}u(x,t) \approx e^{i\tau\mathcal{L}}e^{i\tau\mathcal{N}(u)}u(x,t)$$
(16)

This expression is exact whenever  $\mathcal{L}$  and  $\mathcal{N}$  commute. Otherwise the splitting is first order accurate. Accordingly, we use

$$U(x,t+\tau) = e^{i\tau\mathcal{L}}e^{i\tau\mathcal{N}(U)}U(x,t)$$
(17)

where U(x,t) denotes the approximation of u(x,t).

Next, we introduce the quantity

$$V^m := e^{i\tau \mathcal{N}(U^m)} U^m \tag{18}$$

where  $U^m$  denotes the approximation at the time  $m\tau$ . Then the split-step scheme (17) may be written as

$$U^{m+1} = e^{i\tau\mathcal{L}}V^m. \tag{19}$$

# 4 High order splitting methods for Hamiltonian PDE systems

Symplectic integrators are numerical integrations schemes for Hamiltonian systems, which conserve the symplectic two-form  $dp^d q$  exactly, so that  $(q(0), p(0)) \rightarrow (q(\tau), p(\tau))$  is a canonical transformation. We will show here, how to construct explicit symplectic integrators for a Hamiltonian

$$H = T(p) + V(q). \tag{20}$$

#### 4.1 The Problem

Let A and B be non-commutative operators and  $\tau$  a small real number. For a given positive integer n which will be called the *order of integrator*, find a set of real numbers  $(c_1, c_2, \ldots, c_k)$ and  $(d_1, d_2, \ldots, d_k)$  such that the difference of the exponential function  $\exp[\tau(A+B)]$  and the product of exponential functions

$$\exp(c_1\tau A)\exp(d_1\tau B)\exp(c_2\tau A)\exp(d_2\tau B)\times\cdots\times\exp(c_k\tau A)\exp(d_k\tau B)$$
(21)

is of the order  $\tau^{n+1}$ , i.e., the following equation holds,

$$\exp[\tau(A+B)] = \prod_{i=1}^{k} \exp(c_i \tau A) \exp(d_i \tau B) + o(\tau^{n+1}).$$
(22)

This is equivalent to

$$S(\tau) := \prod_{i=1}^{k} \exp(c_i \tau A) \exp(d_i \tau B) = \exp([\tau(A+B) + o(\tau^{n+1})].$$
(23)

For example, as we saw before, when n = 1, a trivial solution is  $c_1 = d_1 = 1$  (k = 1), and we have

$$\exp[\tau(A+B)] = \exp(\tau A)\exp(\tau B) + o(\tau^2)$$
(24)

When n = 2, we find that  $c_1 = c_2 = \frac{1}{2}, d_1 = 1, d_2 = 0$  (k = 2), thus

$$\exp[\tau(A+B)] = \exp(\frac{1}{2}\tau A) \exp(\tau B) \exp(\frac{1}{2}\tau B) + o(\tau^3)$$
(25)

## 4.2 Basic formulas

We could look closer at this method now, but because it is almost hopeless to obtain a much higher integrator, we skip this and advance to a much better method using the **Baker-Campbell-Hausdorff (BCH) formula**. For any non-commutative operators X and Y, the product of the two exponential functions,  $\exp(X) \exp(Y)$ , can be expressed in the form of a single exponential function as

$$\exp(X)\exp(Y) = \exp(Z)$$

where

$$Z = X + Y + \frac{1}{2}[X, Y] + \frac{1}{12}([X, X, Y] + [Y, Y, X]) + \frac{1}{24}[X, Y, Y, X] - \frac{1}{720}([Y, Y, Y, Y, X] + [X, X, X, X, Y]) + \frac{1}{360}([Y, X, X, X, Y] + [X, Y, Y, Y, X]) + \frac{1}{120}([X, X, Y, Y, X] + [Y, Y, X, X, Y]) + \dots$$
(26)

Here we used the notation of the commutator [X, Y] := XY - YX, and higher order commutators like [X, X, Y] = [X, [X, Y]]. A remarkable feature of this BCH formula is that there appear only commutators of X and Y exept for the linear terms in the series.

By repeated application of the BCH formula (26), we find

$$\exp(X)\exp(Y)\exp(X) = \exp(W),$$

where

$$Z = 2X + Y + \frac{1}{6}[Y, Y, X] - \frac{1}{6}[X, X, Y] + \frac{7}{360}[X, X, X, X, X] - \frac{1}{360}[Y, Y, Y, Y, X] + \frac{1}{90}[X, Y, Y, Y, X] + \frac{1}{45}[Y, X, X, X, Y] - \frac{1}{60}[X, X, Y, Y, X] + \frac{1}{30}[Y, Y, X, X, Y] + \dots$$
(27)

Thus the operator for the 2nd order symplectic integrator (25) can be written in the form

$$S_{2nd}(\tau) := \exp(\frac{1}{2}\tau A) \exp(\tau B) \exp(\frac{1}{2}\tau A) = \exp(\tau\alpha_1 + \tau^3\alpha_3 + \tau^5\alpha_5 + \tau^7\alpha_7 + \dots),$$
(28)

where

$$\alpha_1 := A + B, \quad \alpha_3 = \frac{1}{12}[B, B, A] - \frac{1}{24}[A, A, B], \\ \alpha_5 := \frac{7}{5760}[A, A, A, A, B] + \dots$$

In the expression (28) there exist no terms of even powers of  $\tau$ , i.e.,  $\alpha_2 = \alpha_4 = \alpha_6 = \cdots = 0$ . This comes from the fact that the operator  $S_{2nd}(\tau)$  is symmetric and has the exact time reversibility

$$S(\tau)S(-\tau) = S(-\tau)S(\tau) = identity$$
<sup>(29)</sup>

Indeed this is an example of a more general statement as follows.

**Lemma 1** Let  $S(\tau)$  be an operator of the form (23) which has the time reversibility (29). If we expand  $S(\tau)$  in the from

$$S(\tau) = \exp(\tau\gamma_1 + \tau^2\gamma_2 + \tau^3\gamma_3 + \tau^4\gamma_4 + \dots)$$
(30)

then

$$\gamma_2 = \gamma_4 = \gamma_6 = \dots = 0$$

The proof can be found in [3].

Therefore if a symplectic integrator has a symmetric form so that (29) holds, it is automatically of an even order. Keeping this fact in mind, we now construct symplectic integrators (4th, 6th, 8th, ...) by a symmetric product of symplectic integrators of lower order.

#### 4.3 Symmetric integrator with exact coefficients

A 4th order integrator is obtained by a symmetric repetition (product) of the 2nd order integrator (28) in the form

$$S_{4th}(\tau) := S_{2nd}(x_1\tau)S_{2nd}(x_0\tau)S_{2nd}(x_1\tau)$$
(31)

where  $x_0$  and  $x_1$  are two real unknowns to be determined. If we apply formula (27) to 31, we have

$$S_{4th}(\tau) = \exp[\tau(x_0 + 2x_1)\alpha_1 + \tau^3(x_0^3 + 2x_1^3)\alpha_3 + \tau^5(x_0^5 + 2x_1^5)\alpha_5 + \dots].$$
(32)

In order that (32) gives a 4th order integrator, we need two conditions

$$x_0 + 2x_1 = 1, \quad x_0^3 + 2x_1^3 = 0 \tag{33}$$

so that  $S_{4th}(\tau) = \exp[\tau(A+B) + o(\tau^5)]$ . The real unique solution is obviously

$$x_0 = -\frac{2^{1/3}}{2 - 2^{1/3}}, \quad x_1 = \frac{1}{2 - 2^{1/3}}.$$
 (34)

If we compare the operator (31 with (28), we find the relations between the two sets of coefficients:

$$d_1 = d_3 = x_1, \quad d_2 = x_0, \quad c_1 = c_4 = \frac{1}{2}x_1, \quad c_2 = c_3 = \frac{1}{2}(x_0 + x_1).$$
 (35)

Once a 4th order integrator is found, it is easy to obtain a 6th order integrator using the 4th order one by the same process.

More generally, if a symmetric integrator of order 2n,  $S_{2n}(\tau)$ , is already known, a (2n+2)th order integrator is obtained by the product

$$S_{2n+n}(\tau) := S_{2n}(z_1\tau)S_{2n}(z_0\tau)S_{2n}(z_1\tau), \tag{36}$$

where  $z_0$  and  $z_1$  must satisfy

$$z_0 + 2z_1 = 1, \quad z_0^{2n+1} + 2z_1^{2n+1} = 0$$
(37)

or

$$z_0 = -\frac{2^{1/(2n+1)}}{2 - 2^{1/2(2n+1)}}, z_1 = \frac{1}{2 - 2^{1/2(2n+1)}}.$$
(38)

In this way we can construct symplectic integrators of an arbitrary even order with exact coefficients. However, with this construction, the (2n)th order integrator requires the operator  $S_{2nd}$ ,  $3^{n-1}$  times. This means that the number of steps k is  $k = 3^{n-1} + 1$ , which grows rapidly as n increases. In [3] an alternative method is shown to obtain more economically integrators, though the coefficients cannot be given analytically.

## A computational task split step method

## A.1 Setting

We want to find a stationary 1-soliton solution of (12) by numerical propagation of an initially Gaussian profile

$$u(x,0) = 1.5e^{-x^2} \tag{39}$$

and discarding radiation. We use PML to treat the outgoing radiation, i.e., change the problem to

$$iu_t + \frac{1}{1 + \sigma e^{i\gamma}} \partial_x \left( \frac{1}{1 + \sigma e^{i\gamma}} u_x \right) + |u|^2 u = 0$$

$$\tag{40}$$

in an additional layer on the boundary as shown in [4]. After enough damping to avoid interfering reflection, we apply Dirichlet BC to cut off the remaining radiation.

The  $\mathcal{L}$  will be replaced by

$$\mathcal{L}u := \frac{1}{1 + \sigma e^{i\gamma}} \partial_x \left( \frac{1}{1 + \sigma e^{i\gamma}} u_x \right) \tag{41}$$

in the damping layer.

Although the NLS equation is defined of the real line we need to impose conditions at a finite boundary when it is solved numerically. We will simulate on the interval  $\left[-\frac{1}{2}L, \frac{1}{2}L\right]$ . This interval is divided in N - 50 equal subintervals with grid spacing h, i.e.,

$$h := \frac{L}{N - 50} \tag{42}$$

At both ends of the interval, we will add a layer of 25 intervals of the length h, where we will apply PML. The grid points are denoted by

$$x_j = jh, \qquad j = -\frac{N}{2}, \dots, \frac{N}{2}.$$
 (43)

The approximation of  $u(x_j, m\tau)$  is denoted by  $U_j^m$ .

In order to implement the split-step scheme (18) - (19) in practice, we use the following rational approximation

$$e^{i\tau\mathcal{L}} = (\mathrm{Id} - \theta i\tau\mathcal{L})^{-1}(\mathrm{Id} + (1-\theta)i\tau\mathcal{L})$$
(44)

where  $\theta$  is a free parameter with  $0 \le \theta \le 1$ .

Equation (19) now becomes

$$(\mathrm{Id} - \theta i\tau \mathcal{L})U^{m+1} = (\mathrm{Id} + (1 - \theta)i\tau \mathcal{L})V^m.$$
(45)

The space variable may be discretized by replacing  $\mathcal L$  by  $\mathcal L_h$  where

$$\mathcal{L}_h U_j := (U_{j+1} - 2U_j + U_{j-1})/h^2 \tag{46}$$

for  $j = -\frac{N}{2} + 25, \dots, \frac{N}{2} - 25$  and

$$\mathcal{L}_{h}U_{j} := \frac{1}{(1+\sigma_{j}e^{i\gamma})^{2}} \left( (U_{j+1} - 2U_{j} + U_{j-1})/h^{2} - \frac{\sigma_{j}'e^{i\gamma}}{1+\sigma_{j}e^{i\gamma}} (U_{j+1} - U_{j})/h \right)$$
(47)

for  $j = -\frac{N}{2}, \ldots, -\frac{N}{2} + 24$  or  $j = \frac{N}{2} - 24, \ldots, \frac{N}{2}$ . Hence the scheme (45) may be written in matrix notation as

$$(I - ir\theta \mathbf{S})\mathbf{U}^{m+1} = (I + ir(1 - \theta)\mathbf{S})\mathbf{V}^m$$
(48)

where I is the identity matrix, and

$$r := \frac{\tau}{h^2}, \qquad \mathbf{U} := (U_{-\frac{N}{2}}, \dots, U_{\frac{N}{2}}),$$
(49)

$$V_j^m := e^{i\tau |U_j^m|^2} U_j^m \tag{50}$$

and

$$\mathbf{S} := \begin{pmatrix} b_{-\frac{N}{2}} & c_{-\frac{N}{2}} \\ a_{-\frac{N}{2}+1} & b_{-\frac{N}{2}+1} & c_{-\frac{N}{2}+1} \\ \vdots & \vdots \\ a_{-\frac{N}{2}+24} & b_{-\frac{N}{2}+24} & c_{-\frac{N}{2}+24} \\ \vdots & \vdots \\ a_{-\frac{N}{2}+24} & b_{-\frac{N}{2}+24} & c_{-\frac{N}{2}+24} \\ \vdots & \vdots \\ a_{-\frac{N}{2}-24} & b_{-\frac{N}{2}-24} & c_{-\frac{N}{2}-24} \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ a_{-\frac{N}{2}-24} & b_{-\frac{N}{2}-24} & c_{-\frac{N}{2}-24} \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ a_{-\frac{N}{2}-1} & b_{-\frac{N}{2}-1} & c_{-\frac{N}{2}-1} \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ a_{-\frac{N}{2}-1} & b_{-\frac{N}{2}-1} & c_{-\frac{N}{2}-1} \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ a_{-\frac{N}{2}-1} & b_{-\frac{N}{2}-1} & c_{-\frac{N}{2}-1} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ a_{-\frac{N}{2}-1} & b_{-\frac{N}{2}-1} & c_{-\frac{N}{2}-1} \\ \vdots & \vdots & \vdots & \vdots \\ a_{-\frac{N}{2}-1} & b_{-\frac{N}{2}-1} & b_{-\frac{N}{2}-1} \\ \vdots & \vdots & \vdots \\ a_{-\frac{N}{2}-1} & b_{-\frac{N}{2}-1} & b_{-\frac{N}{2}-1} \\ \vdots & \vdots & \vdots \\ a_{-\frac{N}{2}-1} & b_{-\frac{N}{2}-1} & b_{-\frac{N}{2}-1} \\ \vdots & \vdots & \vdots \\ \vdots & \vdots & \vdots \\ a_{-\frac{N}{2}-1} & b_{-\frac{N}{2}-1} & b_{-\frac{N}{2}-1} \\ \vdots & \vdots \\ \vdots & \vdots & \vdots \\ \vdots & \vdots$$

with

$$a_j := \frac{1}{(1+\sigma_j e^{i\gamma})^2} \tag{52}$$

$$b_j := \frac{1}{(1+\sigma_j e^{i\gamma})^2} \left( -2 + \frac{h\sigma'_j e^{i\gamma}}{1+\sigma_j e^{i\gamma}} \right)$$
(53)

$$c_j := \frac{1}{(1+\sigma_j e^{i\gamma})^2} \left( 1 - \frac{h\sigma'_j e^{i\gamma}}{1+\sigma_j e^{i\gamma}} \right)$$
(54)

The absorbtion parameter decreases in quadratic power to an angle of  $\frac{\pi}{4}$  and with a maximum absorption parameter of 100.

$$\gamma := \frac{\pi}{4} \tag{55}$$

$$\sigma_j := 100 \begin{cases} \left(\frac{j + \left(\frac{N}{2} - 24\right)}{25}\right)^2 & \text{if } j < 0\\ \left(\frac{j - \left(\frac{N}{2} - 24\right)}{25}\right)^2 & \text{if } j > 0 \end{cases}, j \in \left\{-\frac{N}{2}, \dots, -\frac{N}{2} + 24, \frac{N}{2} - 24, \dots, \frac{N}{2}\right\}$$
(56)

$$\sigma'_{j} := 200 \begin{cases} \left(\frac{j + \left(\frac{N}{2} - 24\right)}{25}\right) & \text{if } j < 0\\ \left(\frac{j - \left(\frac{N}{2} - 24\right)}{25}\right) & \text{if } j > 0 \end{cases}, j \in \left\{-\frac{N}{2}, \dots, -\frac{N}{2} + 24, \frac{N}{2} - 24, \dots, \frac{N}{2}\right\}$$
(57)

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